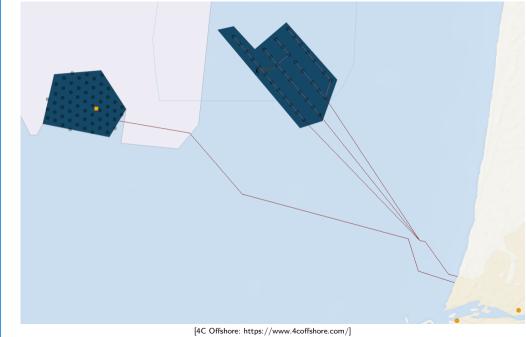
# Flexible and efficient site constraint handling for wind farm layout optimization

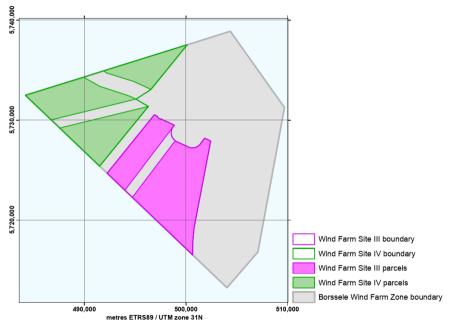
Erik Quaeghebeur

Wind Energy Group — Delft University of Technology

WESC 2019 20 June 2019

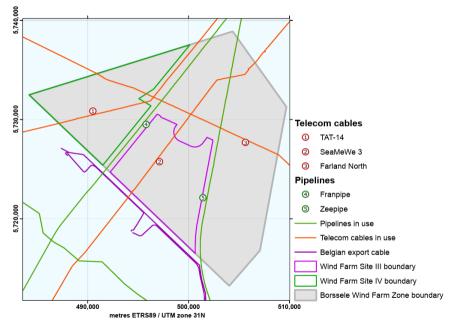






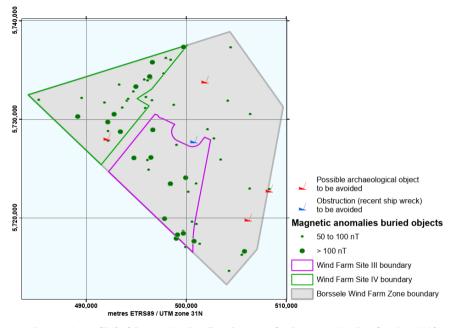
**ŤU**Delft

[Netherlands Enterprise Agency (RVO.nl) Borssele Wind Farm Zone: Project and Site Description Wind Farm Sites III and IV (2016-08)]





[Netherlands Enterprise Agency (RVO.nl) Borssele Wind Farm Zone: Project and Site Description Wind Farm Sites III and IV (2016-08)]



[Netherlands Enterprise Agency (RVO.nl) Borssele Wind Farm Zone: Project and Site Description Wind Farm Sites III and IV (2016-08)]

# So what do real (offshore) sites look like?

A plate of irregularly-cut pieces of Emmental cheese...

- multiple non-connected parts
- non-convex, with concavities of various sizes
- circular exclusion zones strewn around.





 Discretize the possible turbine positions (computationally efficient, but limits optimization approaches)

 Discretize the possible turbine positions (computationally efficient, but limits optimization approaches)

 Divide the site into quadrilaterals and transform those to rectangles (straightforward, but working in transformed space may be inconvenient)

- Discretize the possible turbine positions (computationally efficient, but limits optimization approaches)
- Divide the site into quadrilaterals and transform those to rectangles (straightforward, but working in transformed space may be inconvenient)
- Obscribe the site as a set of polygonal curves and use a ray shooting algorithm (flexible, but limited for correcting violations)

- Discretize the possible turbine positions (computationally efficient, but limits optimization approaches)
- Divide the site into quadrilaterals and transform those to rectangles (straightforward, but working in transformed space may be inconvenient)
- Obscribe the site as a set of polygonal curves and use a ray shooting algorithm (flexible, but limited for correcting violations)
- 4 Various approaches I'm not aware of, but which you'll tell me about later



- Discretize the possible turbine positions (computationally efficient, but limits optimization approaches)
- Divide the site into quadrilaterals and transform those to rectangles (straightforward, but working in transformed space may be inconvenient)
- Obscribe the site as a set of polygonal curves and use a ray shooting algorithm (flexible, but limited for correcting violations)
- ④ Various approaches I'm not aware of, but which you'll tell me about later
- Decomposition into nested convex polygons and calculating closest border point (both flexible and efficient?)

- Discretize the possible turbine positions (computationally efficient, but limits optimization approaches)
- Divide the site into quadrilaterals and transform those to rectangles (straightforward, but working in transformed space may be inconvenient)
- Obscribe the site as a set of polygonal curves and use a ray shooting algorithm (flexible, but limited for correcting violations)
- ④ Various approaches I'm not aware of, but which you'll tell me about later
- Decomposition into nested convex polygons and calculating closest border point (both flexible and efficient?)

Circular constraints need to be added separately to 2, 3, 5!

Linear constraints as the basis



Linear constraints as the basis

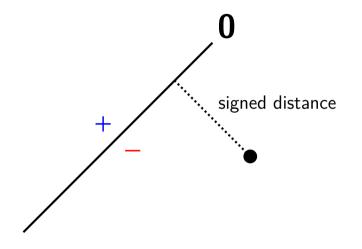
0



Linear constraints as the basis

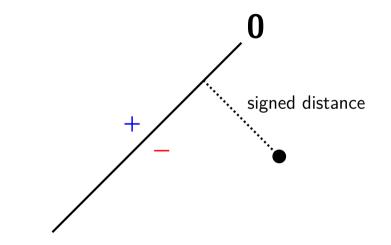










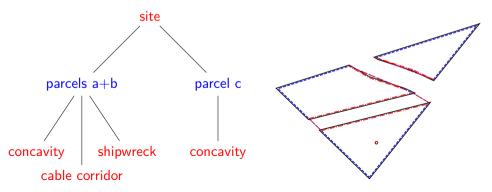


Convex polygons are sets of linear constraints

- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

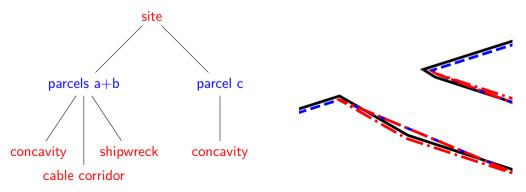
- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

Example for Borssele IV:



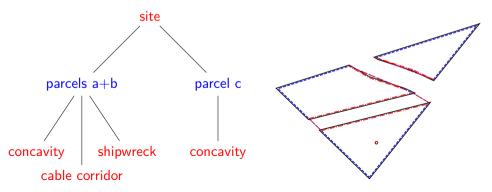
- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

Example for Borssele IV:



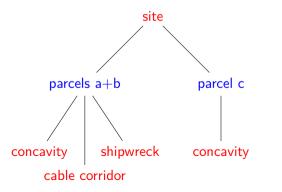
- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

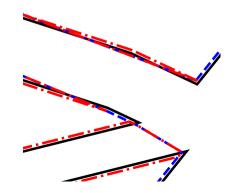
Example for Borssele IV:



- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

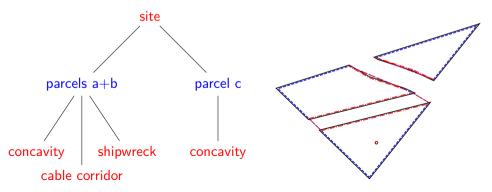
Example for Borssele IV:





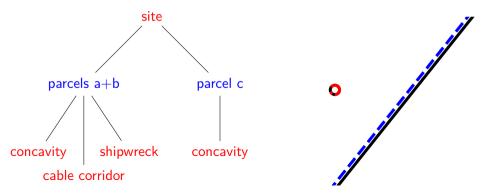
- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

Example for Borssele IV:



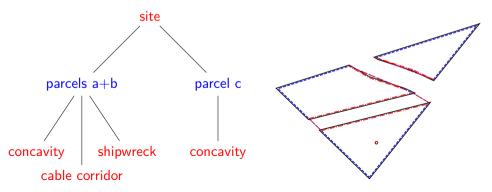
- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

Example for Borssele IV:



- Sites are described as a tree of convex polygons and discs.
- Levels alternate between included and excluded.
- Needs to be done just once, starting from the parcels' vertex lists.

Example for Borssele IV:



```
15
    radius: 8,4628
16
     location:
     - reference_system: ETRS89
18
     - utm zone: 31
       - utm: [492539.33, 5733792.49]
20
     roughness: 0.0001
     parcels:
       - constraints: # IVa + IVb
           - {"x": -0.871282. "v": -0.899564. "1": -1. rotor constraint: true} # WFZ 4. P 75
           - {"x": 1. "v": -0.798527. "1": -0.669320. rotor constraint: true} # P 75. P 74
24
           - {"x": 0.598875, "y": 1., "1": 0.020557, rotor_constraint: true} # P_74, P_73
           - {"x": 0.470030. "y": 1., "1": 0.059057, rotor_constraint: true} # P_73, P_72
26
           - {"x": 0.416783. "v": 1. "1": 0.069992. rotor_constraint: true} # P_72, P_70
28
           - {"x": -0.316693, "y": 1., "1": -0.158119, rotor_constraint: true} # P_70, WFZ_4
         exclusions:
30
           - constraints:
               - {"x": 0.249945. "v": -1.. "1": -0.395467. rotor constraint: true}
               - {"x": -0.249356, "y": 1., "1": 0.274018, rotor_constraint: true}
           - constraints:
               - {"x": -0.573028, "y": -1., "1": -0.118584, rotor_constraint: true}
34
               - {"x": -0.326646. "v": -1.. "1": -0.088503. rotor constraint: true}
           - circle: # 100 m buffer around archeological shipwreck
36
               {center: [-0.058554, -0.658767], radius: 0.011816}
38
       - constraints: # IVc
           - {"x": -0.316691, "y": 1., "1": -0.158109, rotor_constraint: true} # P_82, P_78
           - {"x": 1.. "v": -0.803943, "1": -0.541463, rotor_constraint: true} # P_78, P_79
40
           - {"x": -0.379160. "y": -1., "1": 0.094044, rotor constraint: true} # P 79, P 81
41
42
           - {"x": -0.625480, "y": -1., "1": 0.082657, rotor_constraint: true} # P_81, P_82
         exclusions:
           - constraints:
               - {"x": 0.324121. "v": 1.. "1": -0.096589. rotor constraint: true}
               - {"x": 0.468405, "v": 1., "1": -0.136250, rotor constraint: true}
46
```

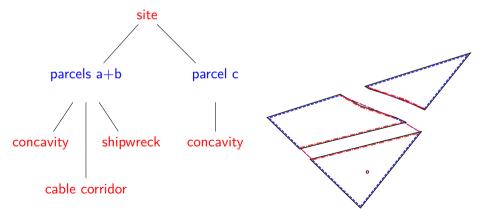
## Deduced from the vertex lists for the parcel boundaries

47	boundaries:
48	- polygon: # <u>IVa</u>
49	- [-0.98795236, -0.15475832] # WFZ_4
50	- [-0.68775564, -0.4455137 ] # P_77 ← not in vertices of IVa+b
51	- [ 0.29881097, -0.19950719] # P_73
52	- [ 0.20536654, -0.15558547] # P_72
53	- [-0.12209072, -0.04862303] # P_71 ← not in vertices of IVa and IVa+b
54	- [-0.31100018, 0.0596274 ] # P_70
55	- polygon: # IVb
56	- [-0.58775308, -0.54237308] # P_76 ← not in vertices of IVa+b
57	- [-0.12313056, -0.99239048] # P_75
58	- [ 0.44168357, -0.28507005] # P.74
59	exclusions:
60	<ul> <li>circle: # 100_m buffer around archeological shipwreck</li> </ul>
61	{center: [-0.058554, -0.658767], radius: 0.011816}
62	- polygon: # IVc
63	$-$ [-0.08008326, 0.13274754] # P_82
64	- [-0.04622915, 0.11157248] # P_81
65	- $[0.27488267, 0.00749325] # P.80 \leftarrow not in vertices of IVC$
66	- [ 0.47291443, -0.08526582] # P_79
67	- [ 0.89693565, 0.44216109] # P_78
68	

- Walk the tree from root to leaves.
- Only check the turbines inside the parent.

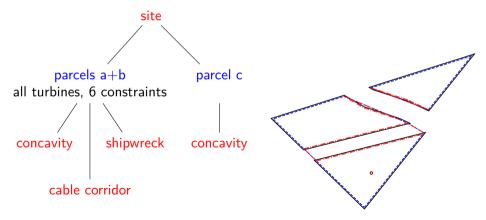
- Walk the tree from root to leaves.
- Only check the turbines inside the parent.

#### Example for Borssele IV:



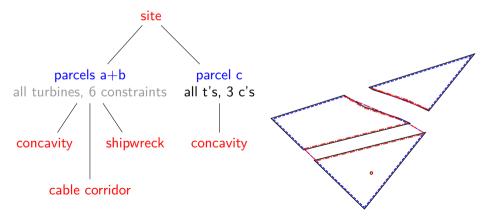
- Walk the tree from root to leaves.
- Only check the turbines inside the parent.

#### Example for Borssele IV:



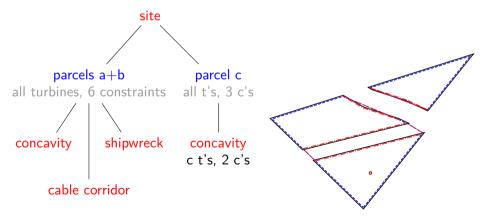
- Walk the tree from root to leaves.
- Only check the turbines inside the parent.

#### Example for Borssele IV:



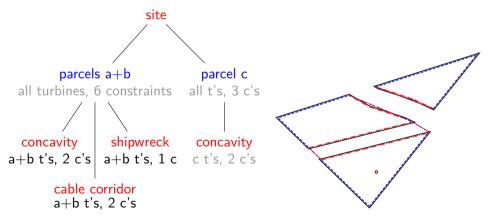
- Walk the tree from root to leaves.
- Only check the turbines inside the parent.

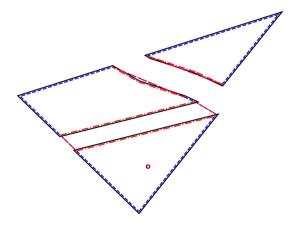
#### Example for Borssele IV:



- Walk the tree from root to leaves.
- Only check the turbines inside the parent.

#### Example for Borssele IV:

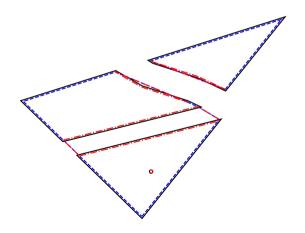




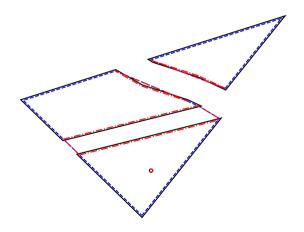


1 Assume constraint check done;

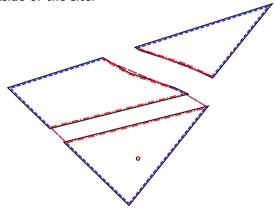
only consider turbines violating site constraints.



- Assume constraint check done; only consider turbines violating site constraints.
- 2 Determine closest point on *all* violated constraints (the *candidates*).



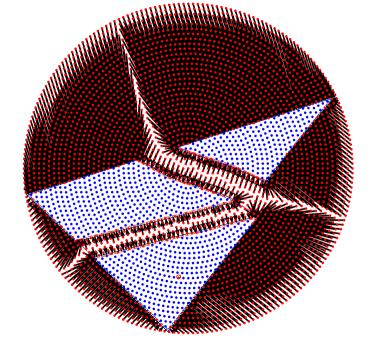
- Assume constraint check done; only consider turbines violating site constraints.
- 2 Determine closest point on *all* violated constraints (the *candidates*).
- 3 Remove candidates that fall outside of the site.



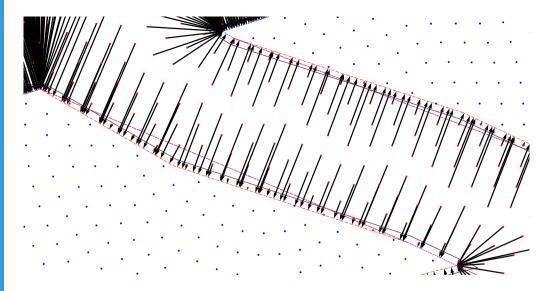


- Assume constraint check done; only consider turbines violating site constraints.
- 2 Determine closest point on *all* violated constraints (the *candidates*).
- 3 Remove candidates that fall outside of the site.
- For parcels without a candidate, take the closest parcel vertex as the candidate.

- Assume constraint check done; only consider turbines violating site constraints.
- 2 Determine closest point on *all* violated constraints (the *candidates*).
- 3 Remove candidates that fall outside of the site.
- For parcels without a candidate, take the closest parcel vertex as the candidate.
- 5 Take the closest candidate as the correction.

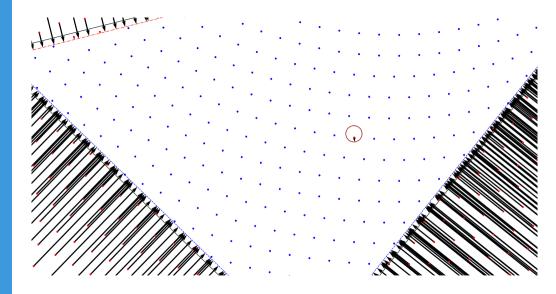






(My current implementation differs from the algorithm sketched.)







### Conclusions

### • Site constraint handling deserves more attention.

### • Efficient approaches are possible.



### To do

- Decent overview of constraint handling approaches. (Your input is appreciated!)
- Efficiency relative to other approaches.
- Actual characterization of computational complexity.
- Better implementation of correction algorithm.
- Restriction to 'simple' decompositions?



### Thanks! Questions?

